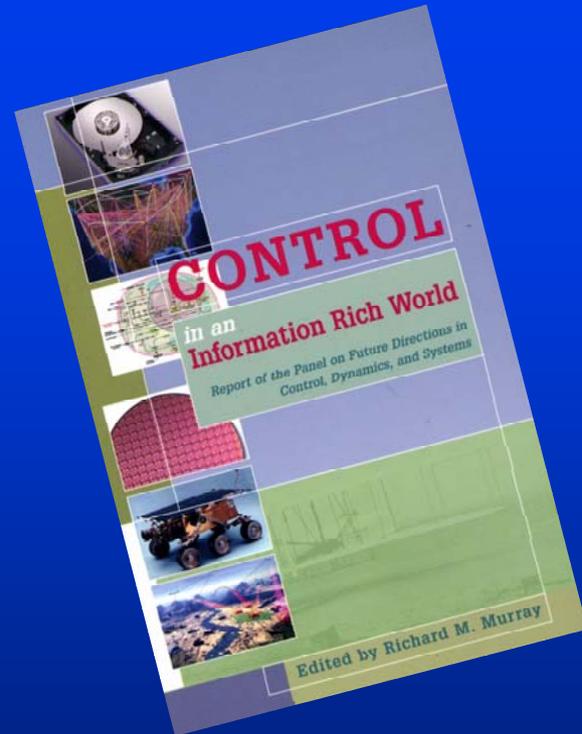
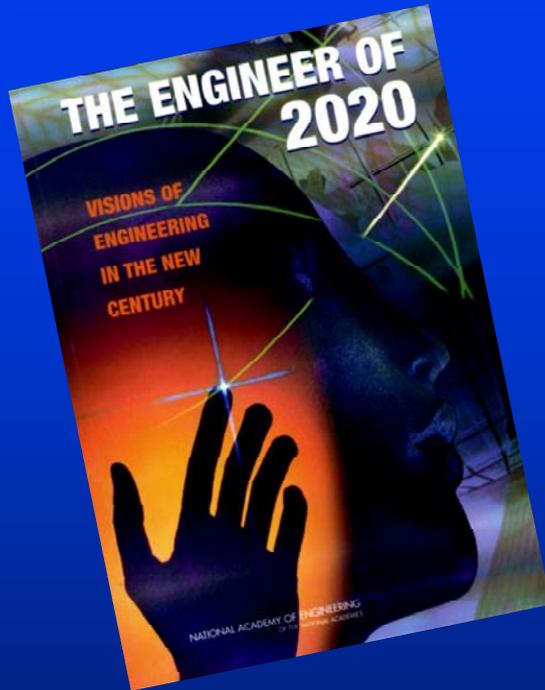


# Present Developments in Control Applications

K. J. Åström

Lund University  
Sweden

# Acknowledgements



*Numerous friends and colleagues in industry and academia*

# How Control Developed

- **Early use**
- **The Field Emerges**
- **The Second Phase**
- **The Third Phase?**

# Control Emerges

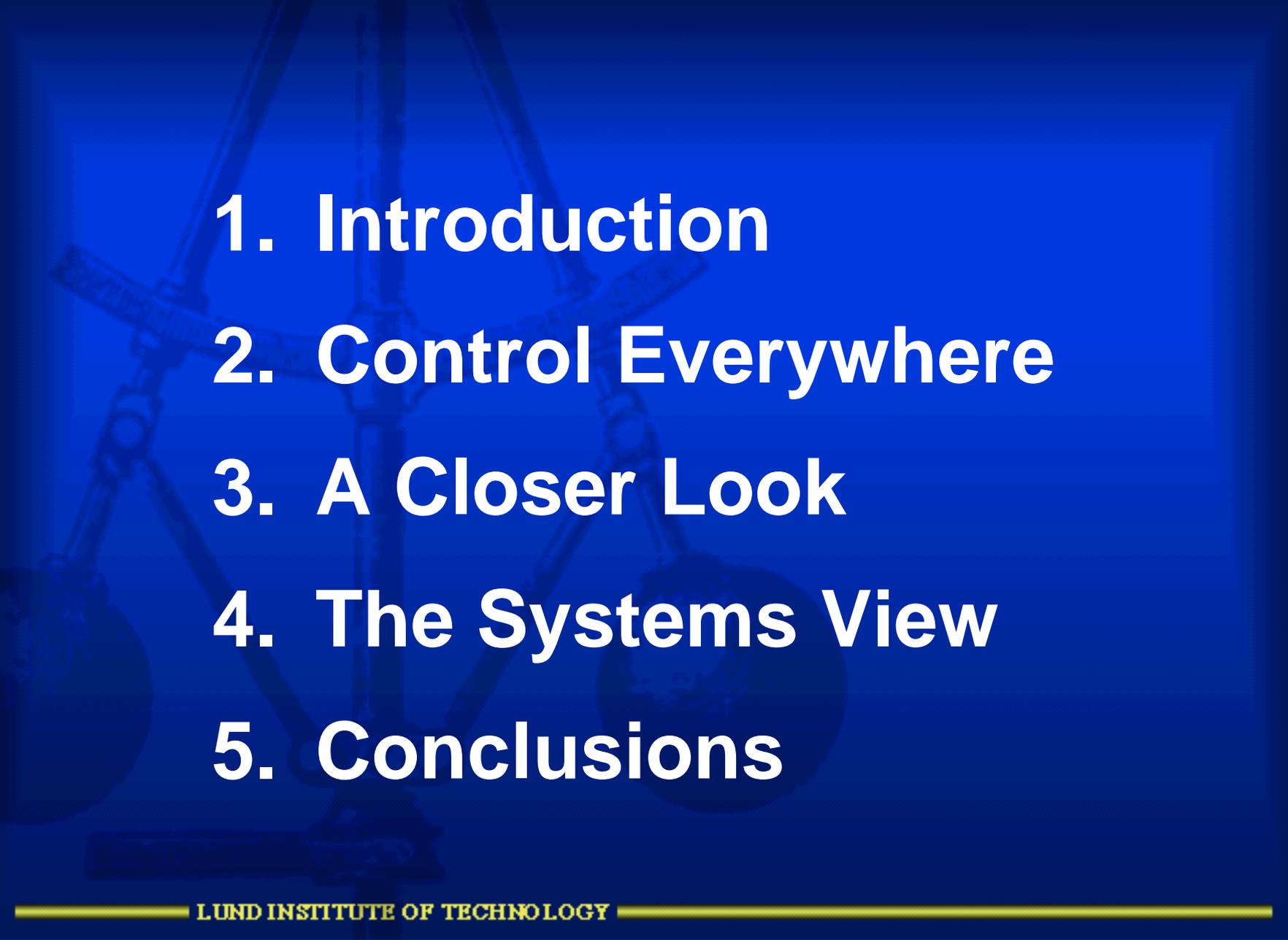
- **Drivers: gun control, radar ...**
- **Block diagrams, transfer functions**
- **Design tools: graphical**
- **Analog computing**
- **Holistic view of theory & applications**

# The Second Phase

- **Drivers: space, computer control, mathematics**
- **Rapid growth of subspecialities**
- **Optimal, stochastic, nonlinear, ...**
- **Computational tools**
- **Impressive development of theory**
- **Holistic view was lost**

# The Third Phase?

- **Drivers: embedded system, networks, biology, physics, ...**
- **Autonomy, distribution**
- **Exploding applications**
- **Hardware and software platforms**
- **Holistic view will be recovered?**

- 
- 1. Introduction**
  - 2. Control Everywhere**
  - 3. A Closer Look**
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# Breakthrough Technologies

Everything will, in some sense, be smart; that is, every product, every service, and every bit of infrastructure will be attuned to the needs of the humans it serves and will adapt its behavior to those needs.

Sensing, actuation, and control

*NAE The Engineer of 2020*

# Control Everywhere

- **Manufacturing**
- **Products**
- **Ideas**
- **Why?**

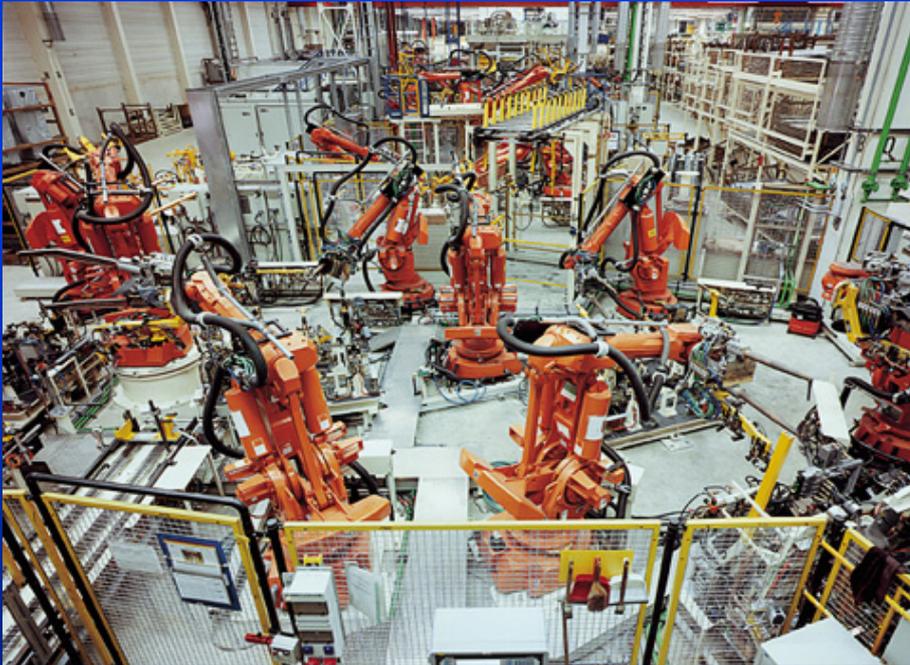
# Power Generation and Distribution



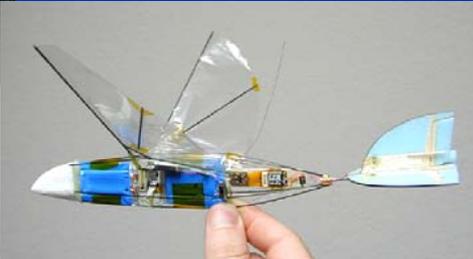
# Process Control



# Discrete Manufacturing



# Vehicles



# Consumer Electronics



# Biomedical

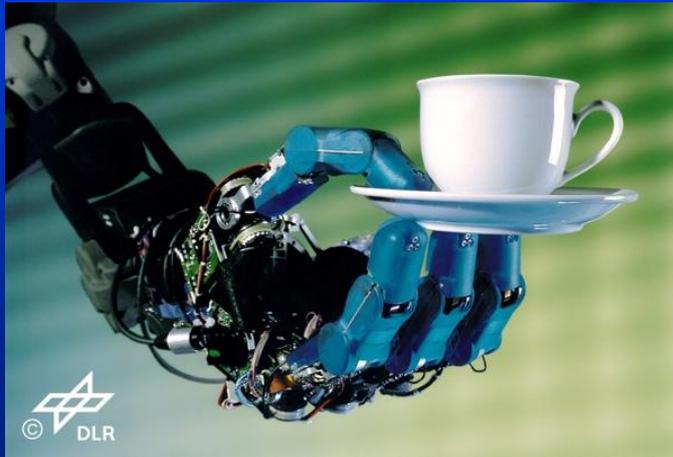


# DLR Robots and Hands

*LWR III: 7 joints weight/load =1.5*

*150 W, 3 cables*

*Hand II: 13 joints 3 kg finger force*



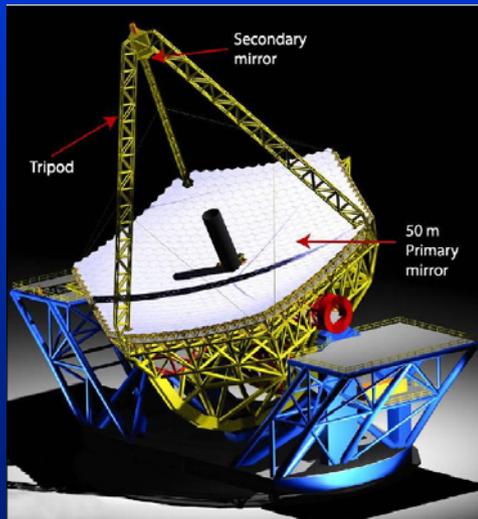
*Gerd Hirzinger DLR*

# Science

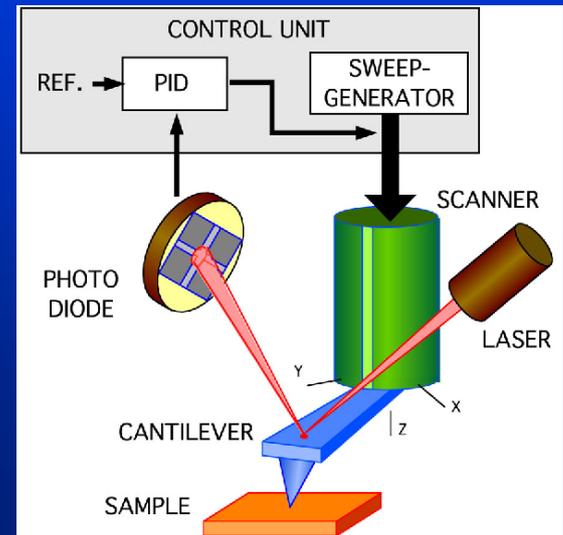
Ideas: Feedback and systems

Instruments: mega to nano

## Adaptive Optics



## Atomic Force Microscope



# Biology

**Feedback is a central feature of life. The process of feedback governs how we grow, respond to stress and challenge, and regulate factors such as body temperature, blood pressure, and cholesterol level.**

**The mechanisms operate at every level, from the interaction of proteins in cells to the interaction of organisms in complex ecologies.**

# Key Drivers

- **Insight and understanding**
- **Knowledge and education**
- **Power of feedback and computing**
- **Tools**
- **Control a commodity?**

# The Power of Feedback

- Good systems from bad components
- Attenuate disturbances
- Stabilize unstable system
- Shape behavior
- Risk of instability

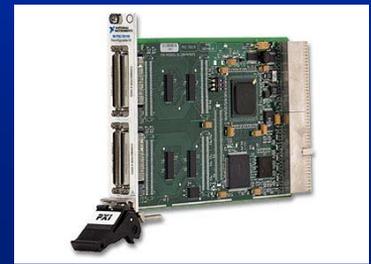
# Control and Computing

- Vannevar Bush 1927. Engineering can progress no faster than the mathematical analysis on which it is based. Formal mathematics is frequently inadequate for numerous problems, a mechanical solution offers the most promise.
- Herman Goldstine 1962. When things change by two orders of magnitude it is revolution not evolution.
- Gordon Moore 1965: The number of transistors per square inch on integrated circuits has doubled in approximately 18 months.

# Tools



- Sensors, actuators, process interfaces
- Computers, signal processors, FPGA
- Tools for modeling, analysis, simulation and design
- Operating systems, automatic code generation



# NASA's X43-A Scramjet Achieves Record-Breaking Mach 10 Speed Using MathWorks Tools for Model-Based Design

## The Challenge

To design and automatically generate flight control software for a scramjet vehicle traveling at Mach 10 speed

## The Solution

Use Simulink® to model and validate control systems, Real-Time Workshop® to automatically generate flight code, and MATLAB® to process and analyze post-flight data

## The Results

Reduced development time by months  
Accurately predicted separation clearance  
Aided in achieving SEI CMM Level 5 process rating



The X43-A on its record-setting flight.

*Our autopilot worked on the first try, which is amazing given that a vehicle like this had never been flown before. MathWorks tools helped us design and implement control systems that kept the vehicle stable throughout the flight."*

*Dave Bose,  
Analytical Mechanics Associates*

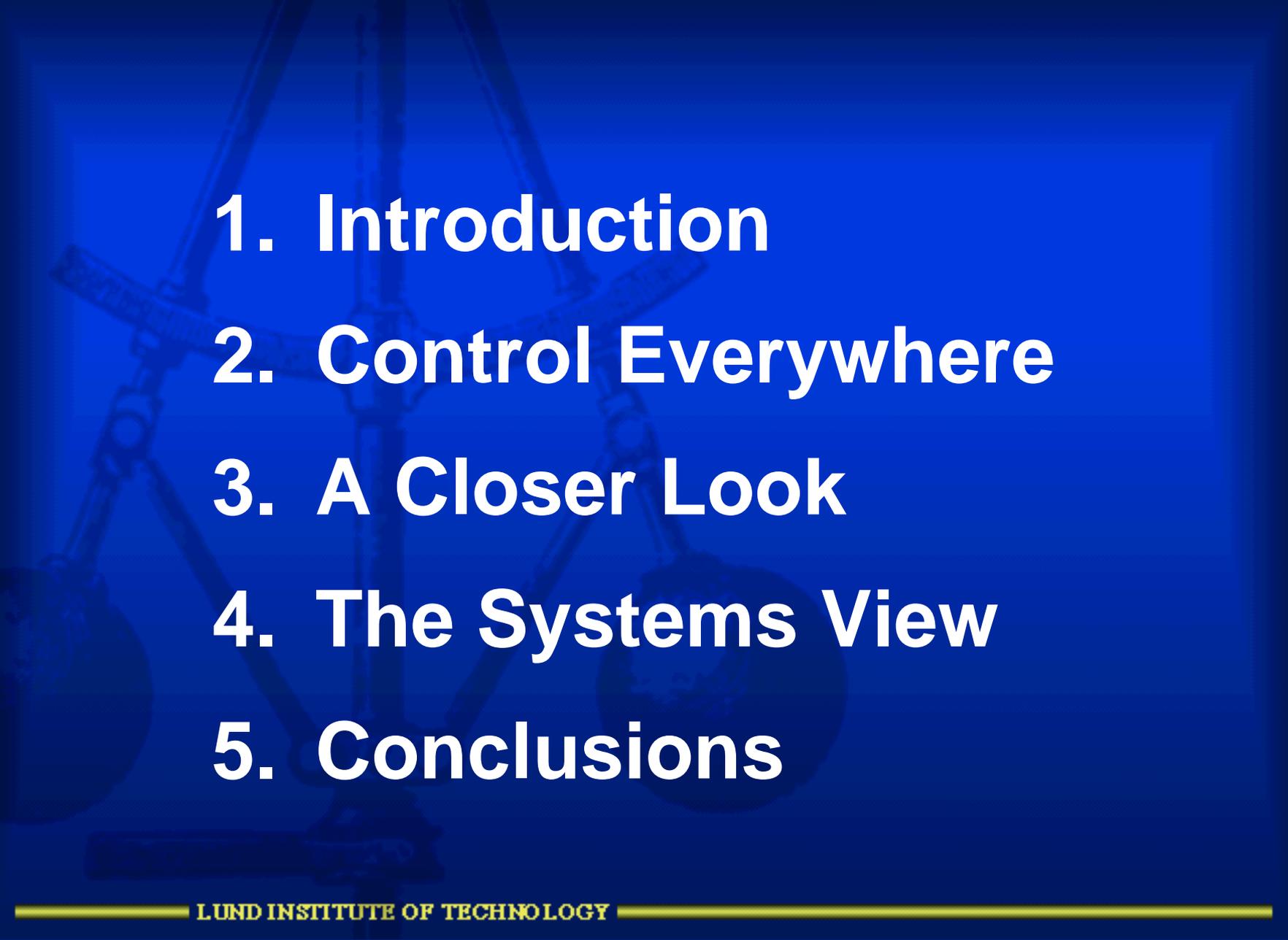
# Rapid Control

NI CompactRIO

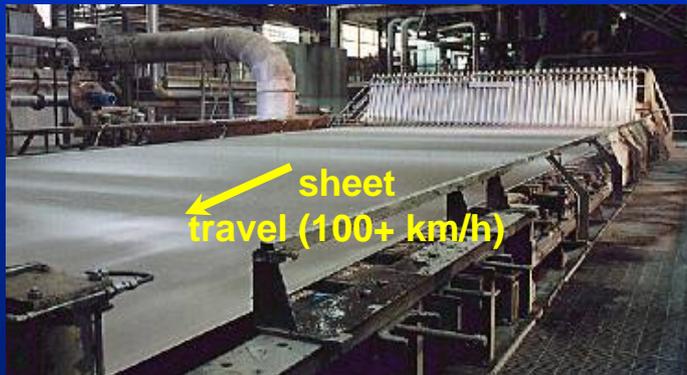
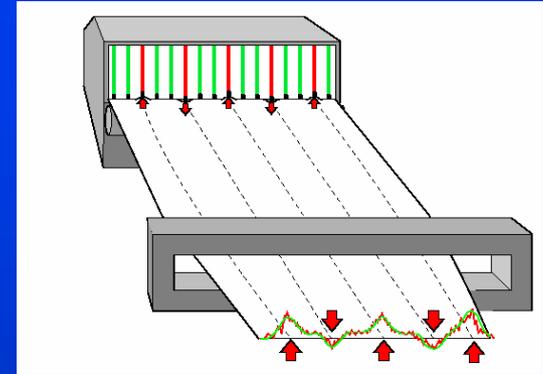
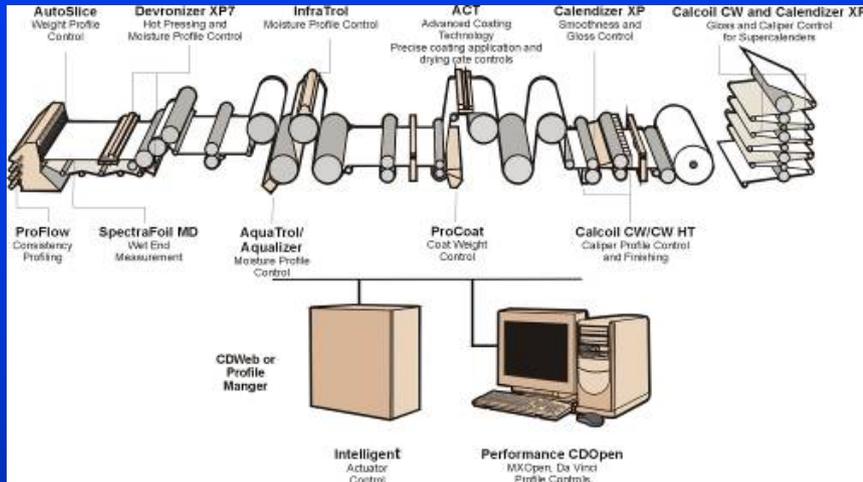


*Drivven: "We prototyped a full-authority engine control system ... in just 3 man-months. In past projects, it took us at least 2 man-years and over \$500,000 to develop similar ECU systems."*



- 
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# Cross Direction Control



Several hundred sensors and actuators, millisecond operation, controlling paper thickness to within microns!

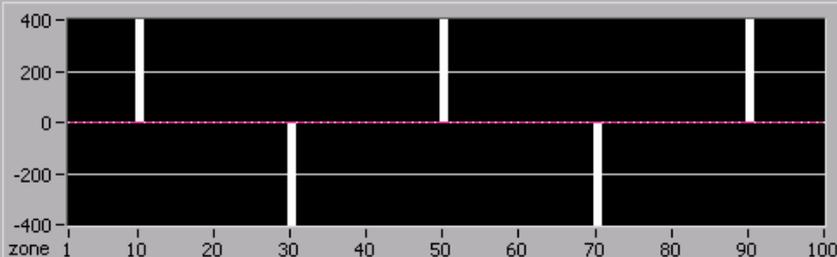
**Honeywell** Laboratories

PROCESS IDENTIFICATION

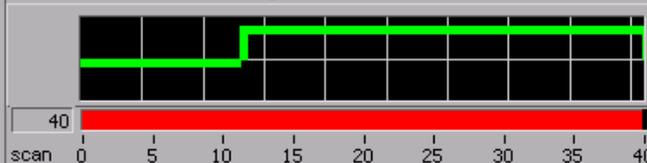
AutoSlice-CDW

Automatic ID OFF

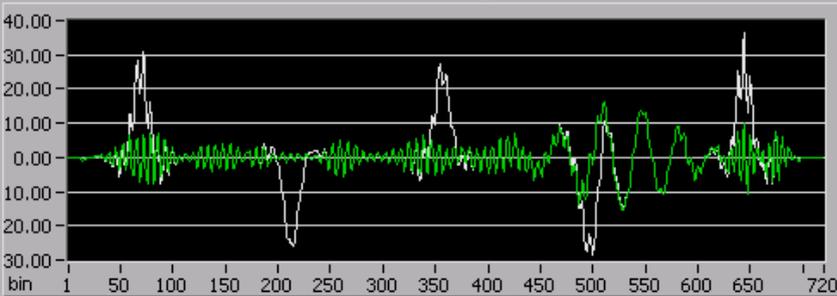
CD Bump Test Excitation Profile



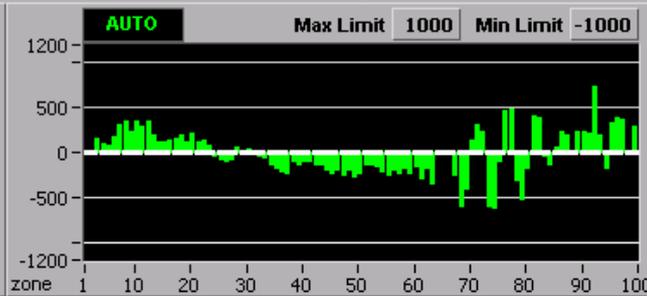
MD Bump Test Excitation Pattern



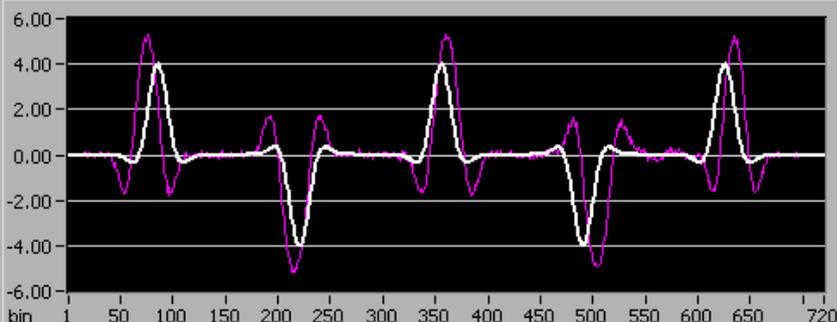
Current and Predicted High Resolution Profile



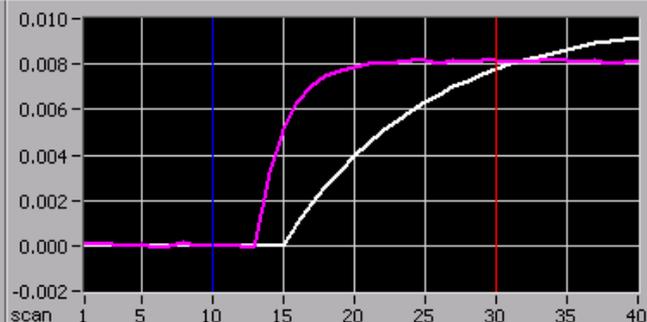
Actuator Setpoints Profile



CD Model Identification



Dynamic Model Identification



Low Sheet Edge	1.50	Shrinkage	6.30	High Sheet Edge	719.50
Low Actuator Offset	-321.36	Confidence	0.58	High Actuator Offset	-322.21

Controller Gain	0.01775	Time Constant	47.06
Time Delay	20.01	Average Scan Time	10.00

License Info...

Current Grade

My Grade

Scanner 1 Status

ODX Link Status

NO CONNECTION

Bump Test Configuration

Process Identification

Alignment Implementation

CD Control Tuning

Tuning Implementation

Reports

Color Topography

Start ODXLink

Stop ODXLink

Print Screen

Minimize IntelliMap

Exit IntelliMap

Start Bump Test

Save/Load Bump Test Data

Identify Overall Model

Spatial Model Identification

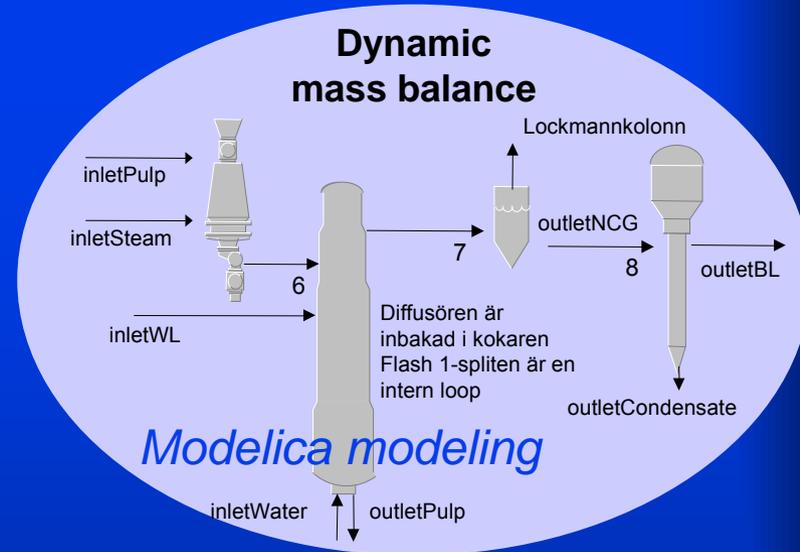
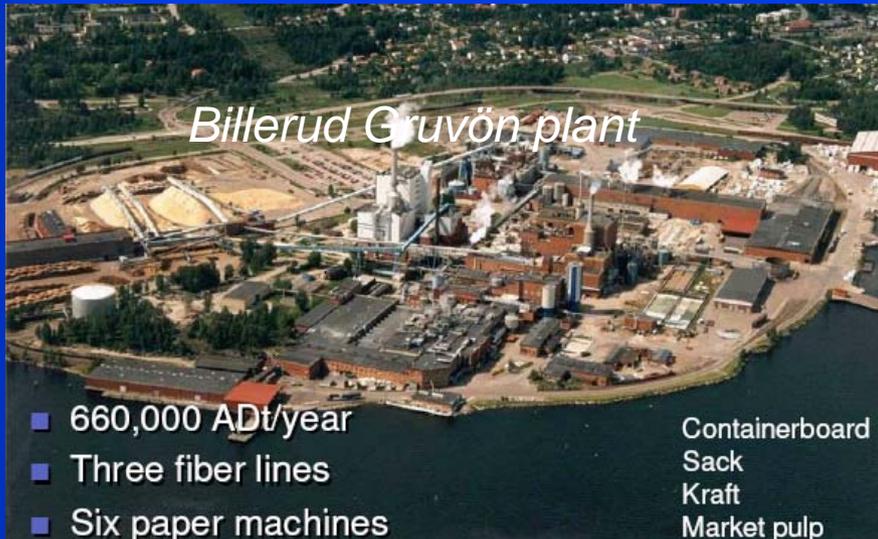
Dynamic Model Identification

Shrinkage Model Identification

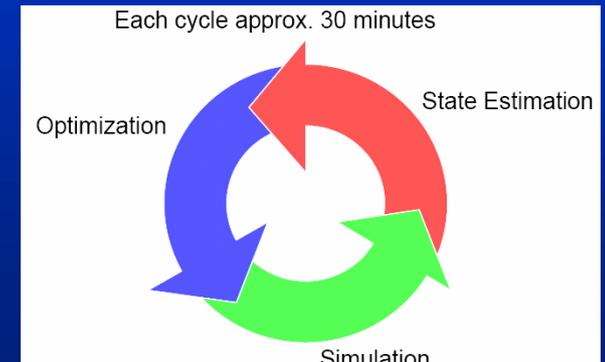
Spatial Control Fine Tuning

Dynamic Control Fine Tuning

# Mill Wide Control



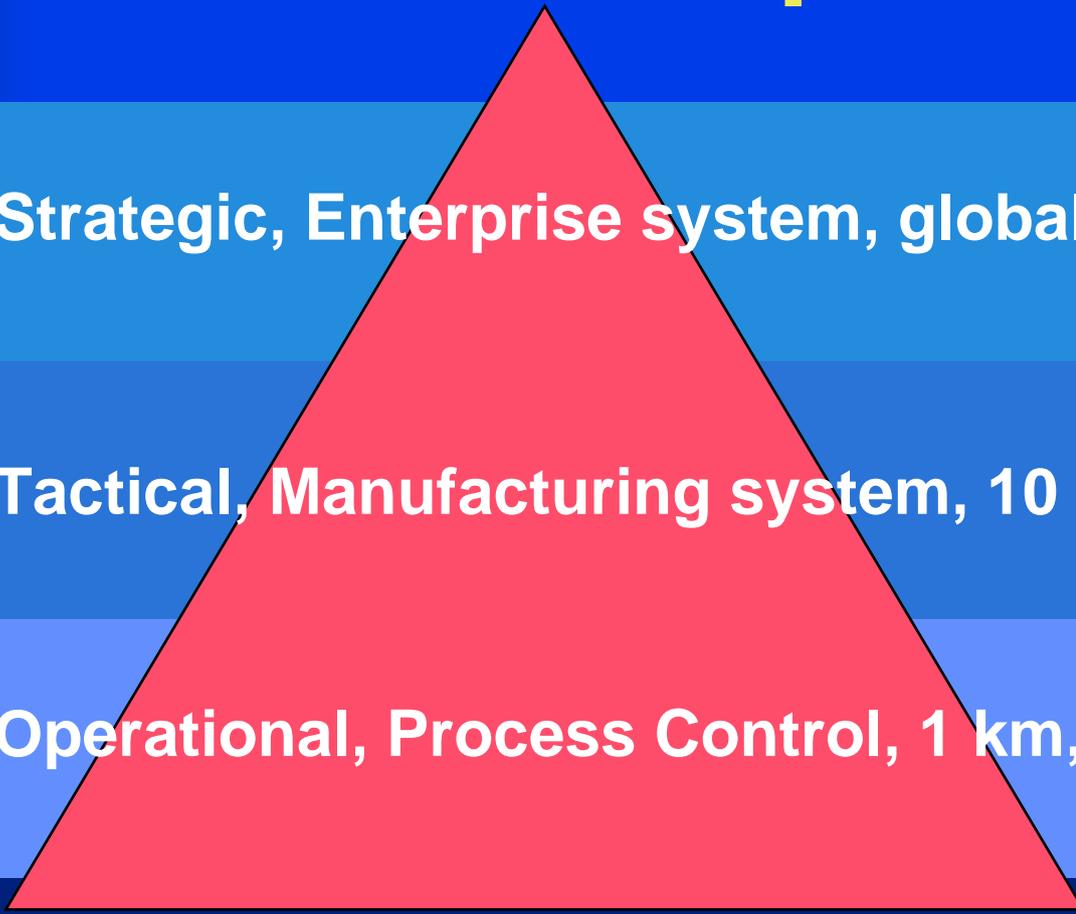
25	Production units
38	Buffer tanks
250	Streams
250	Measurements
2500	Variables



*Slide from Alf Isaksson*



# Global Enterprise Control



Strategic, Enterprise system, global, 1-10 years

Tactical, Manufacturing system, 10 km, year, shift,

Operational, Process Control, 1 km, shift, ms

# Automotive

Engine control

Power trains

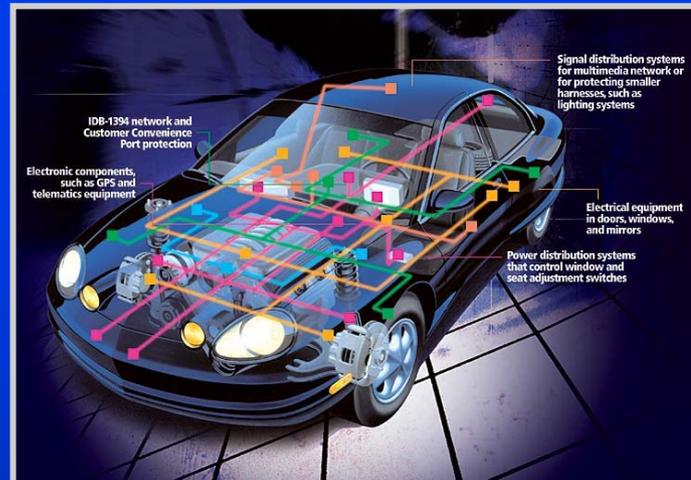
Cruise control

Adaptive cruise control

Traction control

Lane guidance assistance

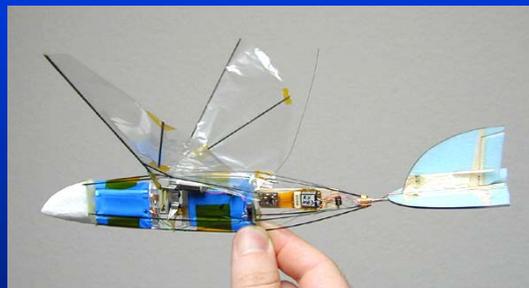
Platooning



# Automotive

- **Strongly enhanced performance**
- **Strong technology driver**
- **Large numbers (microcontroller)**
- **Low costs**
- **Safe design and operation of networked embedded systems**

# Aerospace



# Boeing 777 1995



Pilot crew 1280 networked processors

# Unmanned Air Vehicles

Relative Level of Autonomy

Challenge: Replacing the Pilot with Software



**Lightning Bug**

- Target Drone
- C-130 Launched
- Operator Controlled
- Limited Autopilot



**Tomahawk**

- Autopilot
- Tgt Recognition
- Multi Targeting
- Launch & Forget



**Predator**

- Autopilot
- Piloted T-O & Landing
- Racetrack
- Surveillance
- Route Replanning



**UCAV**

- T.O & Landing
- Navigation
- ESM Search
- RADAR Pointing/Cueing/Transmission
- SEAD
- Air-to-Ground
- In-flight Retargeting
- Collaborative AOA Measurement



**UASV**

- Autonomous
- Evasive Maneuvers
- Extreme Performance
- T.O & Landing
- Navigation
- Multi-ship Trajectories (TF/TA)
- Inter-Ship Collaboration
- Information Mining
- Sensor Control
- ATR
- Weapon Delivery
- A/G & A/A
- BDA
- Manned A/C Augmentation
- In-flight Retargeting
- N on N Engagement

1960s

1980s

2000

2010

2015-20

Time

# Cooperative Control is Hard

## Coupling

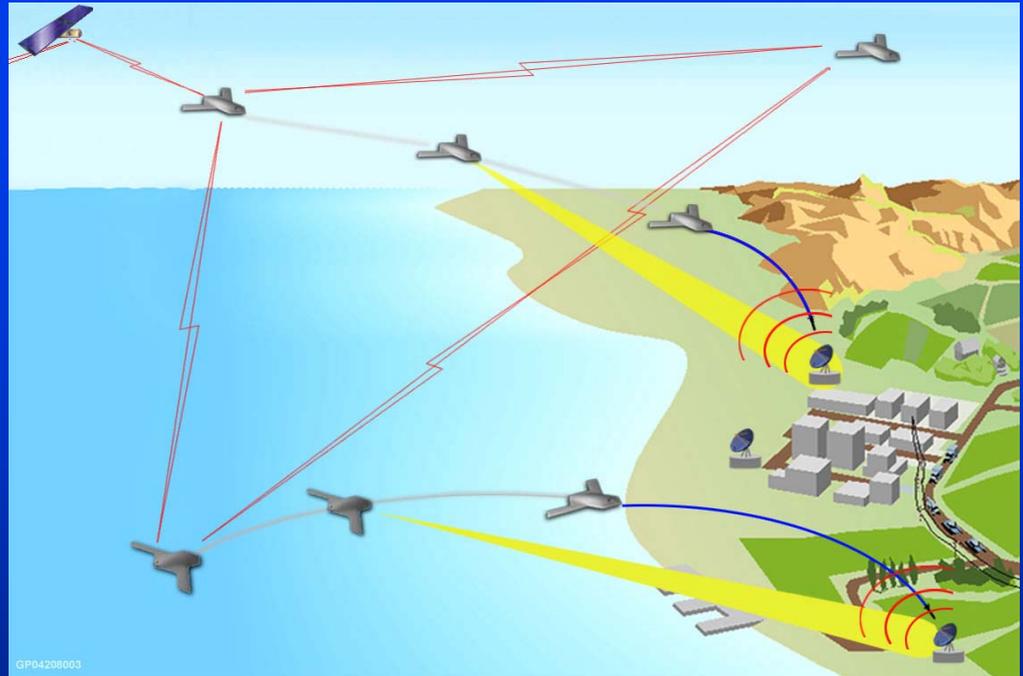
- Precedence constraints
- Joint tasks
- On-line computation

## Uncertainty

- Target locations
- Threat environment
- Enemy actions
- Engagement outcomes

## Communication Constraints

- Asynchronous COMM
- Limited throughput
- Delays and outages



*Siva Banda AFRL*

# Scientific Instruments

- **Scientists (physics, biology)**
- **Revolutionary properties**
- **Control is mission critical**
- **Control is performance critical**

# Atomic Force Microscope

Laser

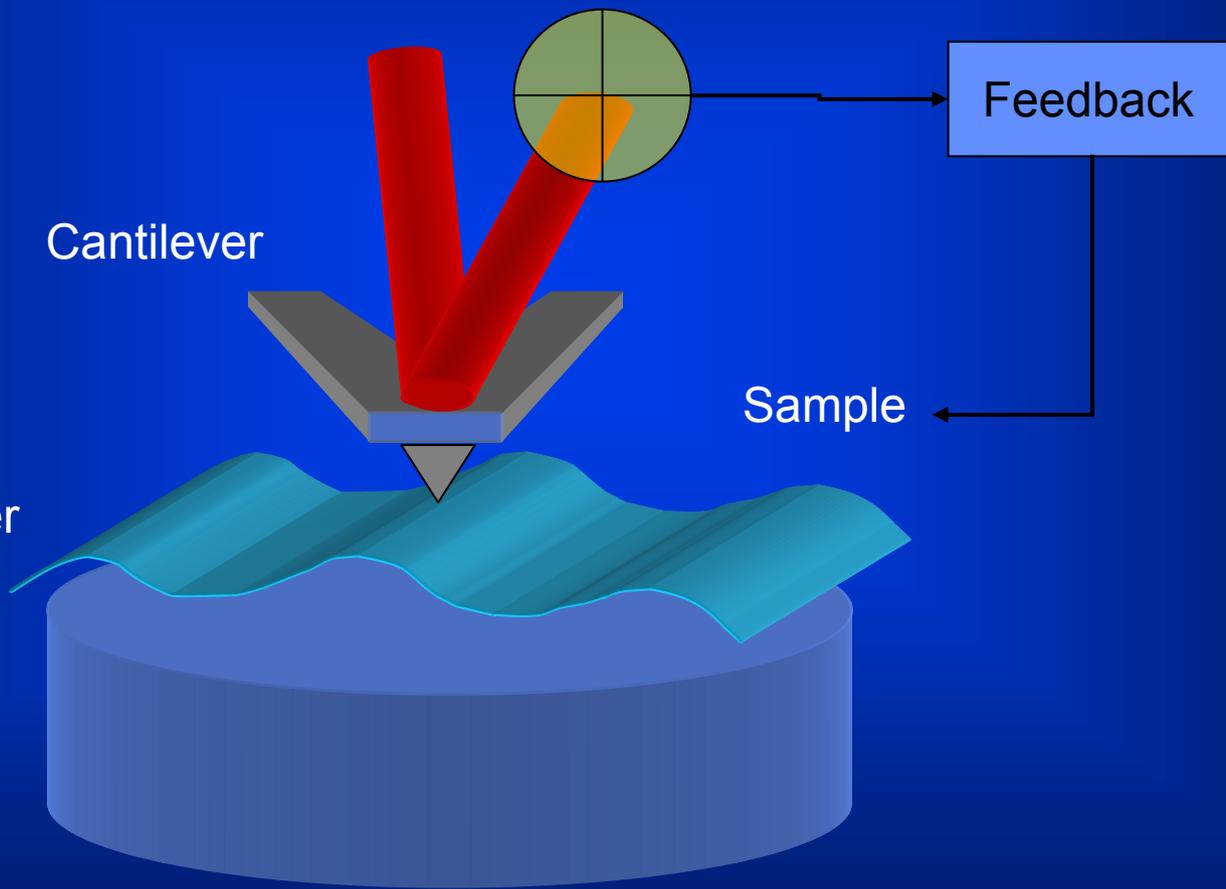
Photodiode

Cantilever

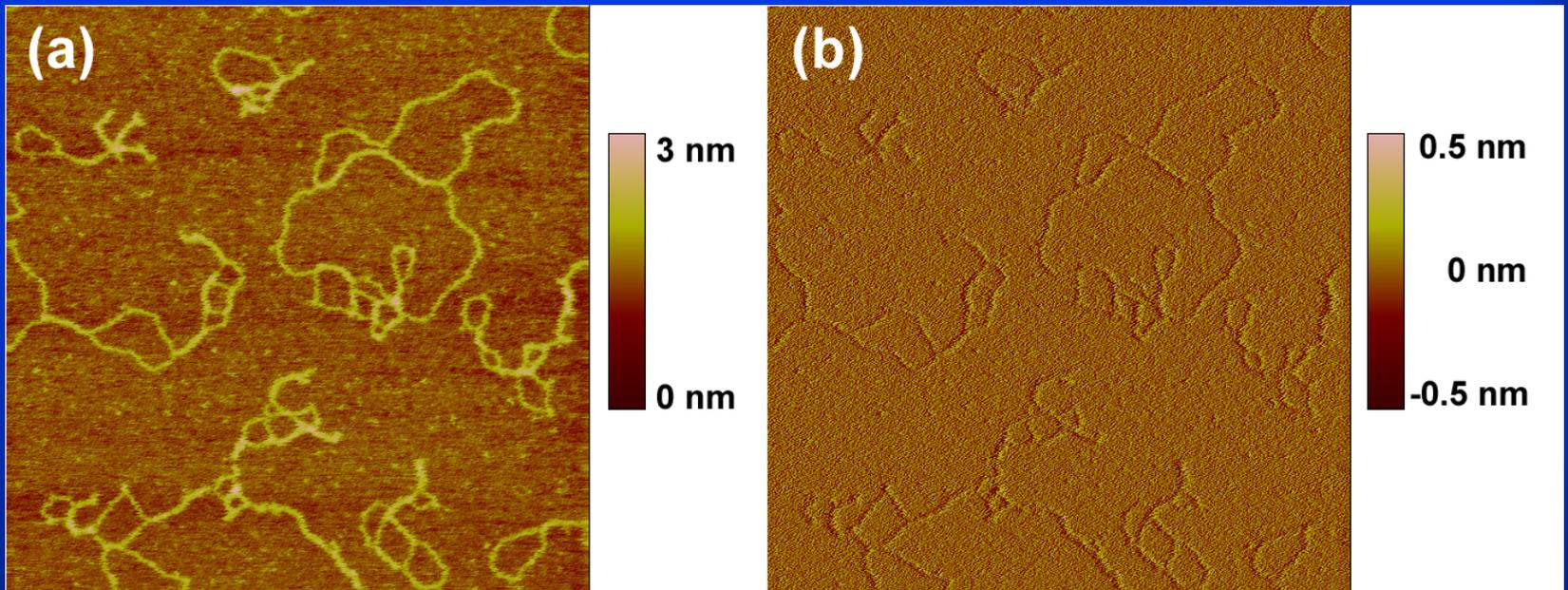
Feedback

Sample

Piezoscanner



# Image of DNA String



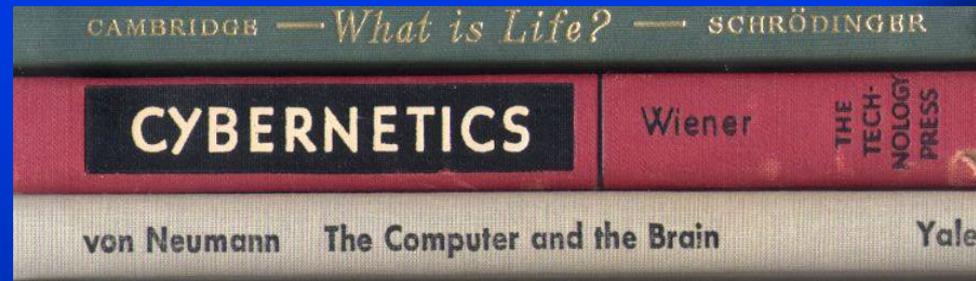
# Impact of Control

- **Enabling technology**
- **Increased scan rate**
- **Improved image quality**
- **Integrated process and control design**
- **Tuning tools for easy use**

# Biology

A long tradition

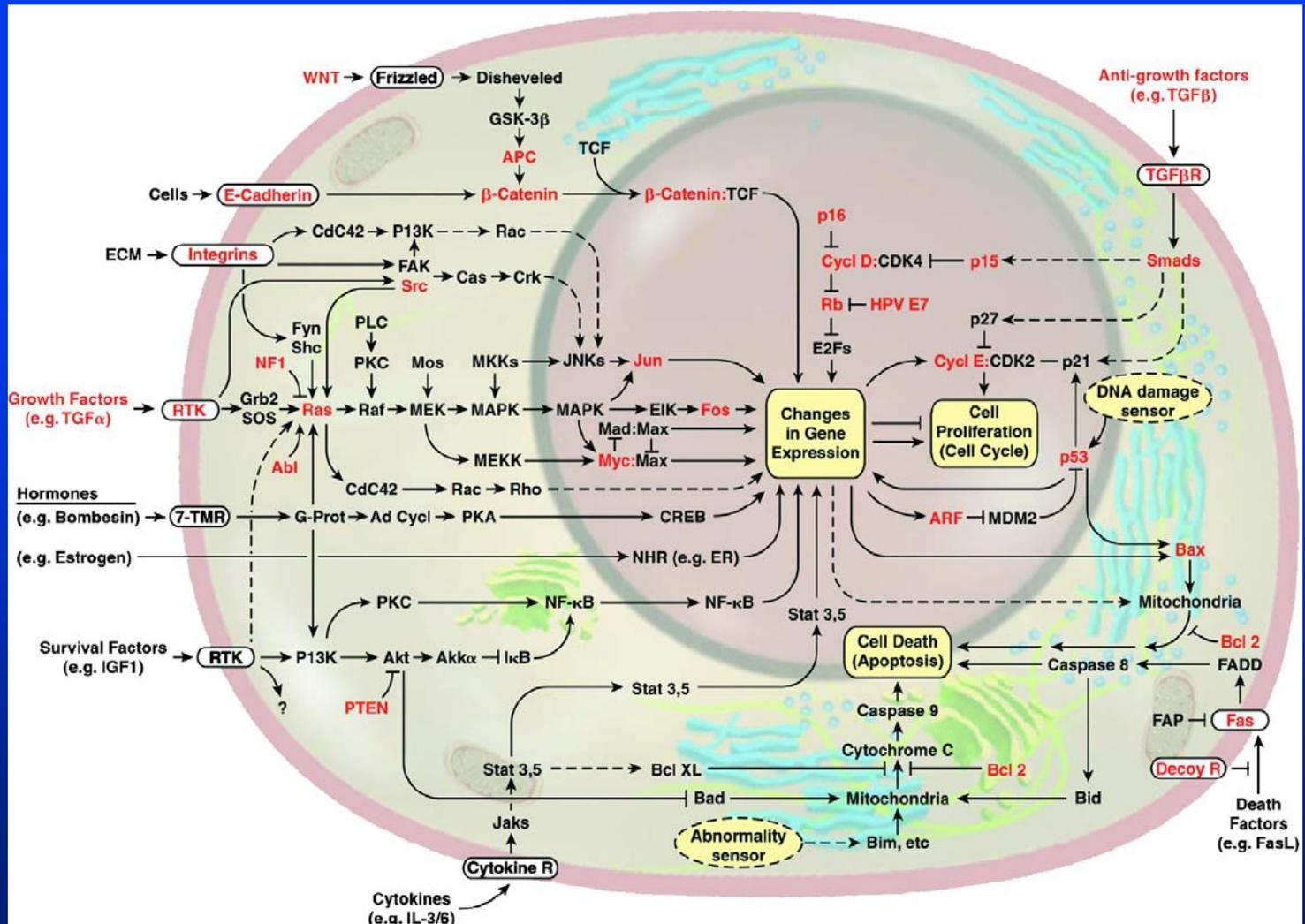
- Schrödinger 1944
- Wiener 1948
- von Neumann 1958
- Bellman Mathematical Biosciences
- Understanding dynamics and control crucial
- What is new?

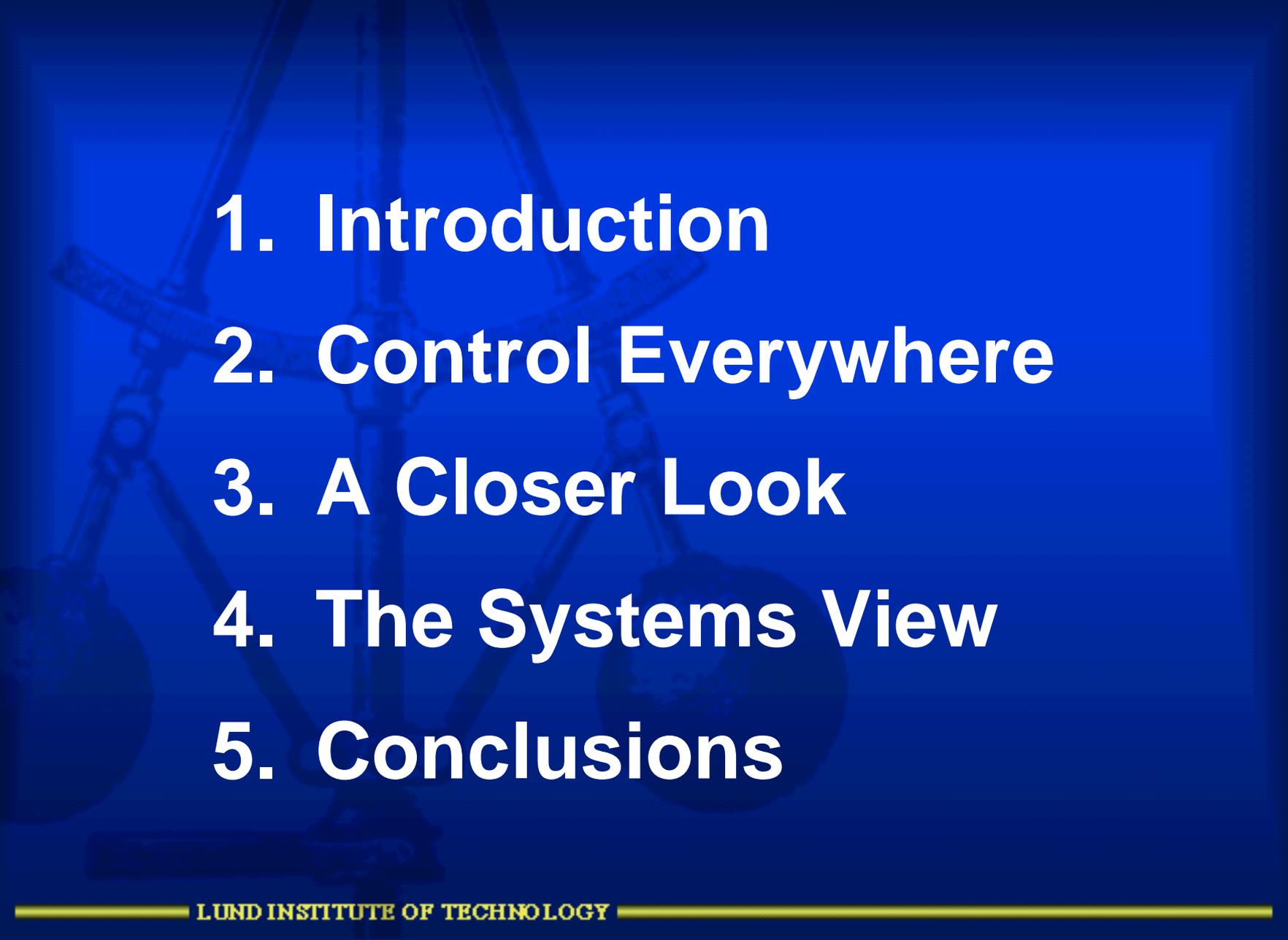


# Systems Biology

Leading biologists have recognized that new systems-level knowledge is urgently required in order to conceptualize and organize the revolutionary developments taking place in the biological sciences, and new academic departments and educational programs are being established at major universities, particularly in Europe and in the United States

# Signaling Circuit in Mammalian Cell



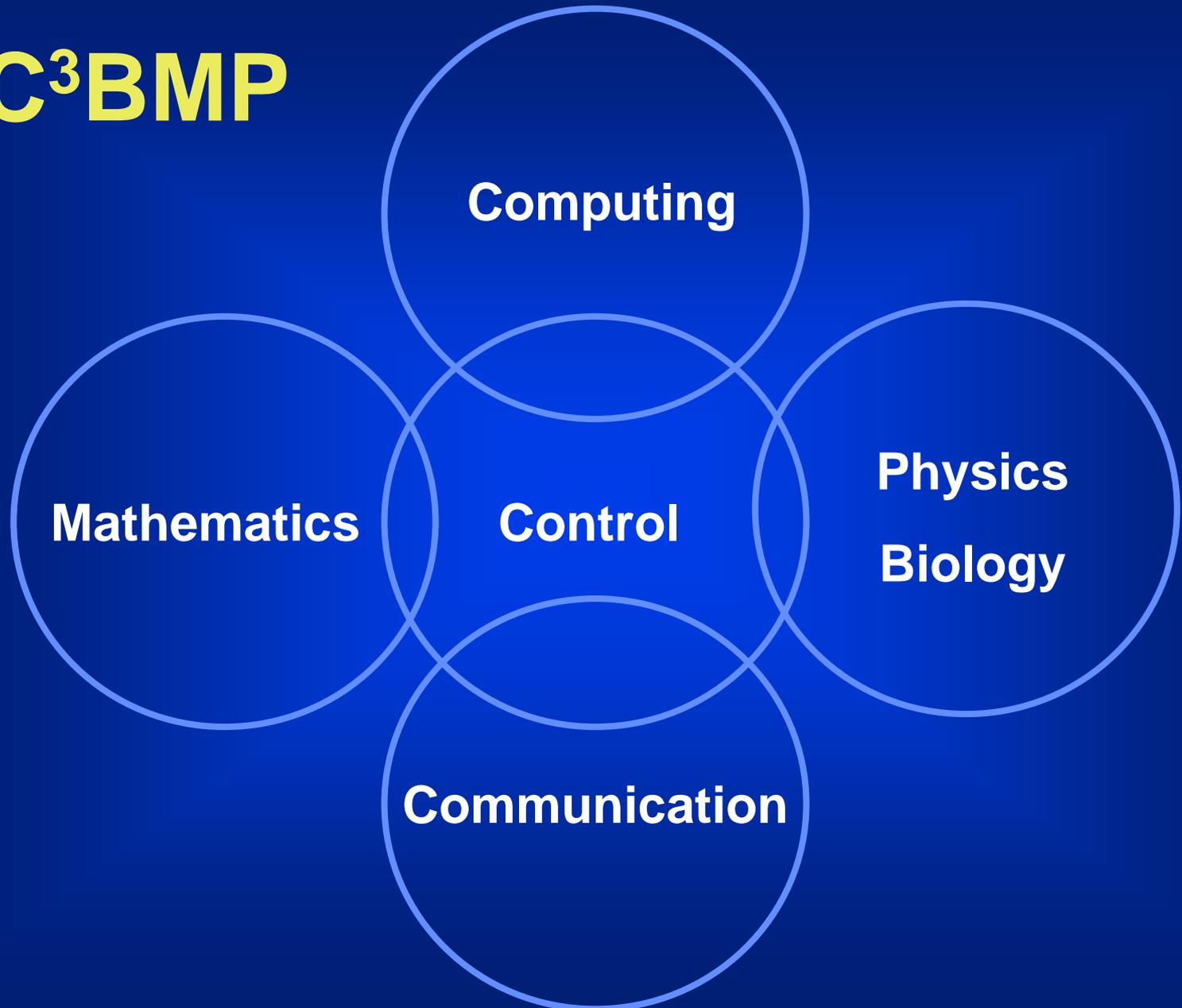
- 
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# The Systems Perspective

In the past steady increases in knowledge has spawned new microdisciplines within engineering. However, contemporary challenges

- from biomedical devices to complex manufacturing designs to large systems of networked devices
- increasingly require a systems perspective

# C<sup>3</sup>BMP



# Modeling and Simulation

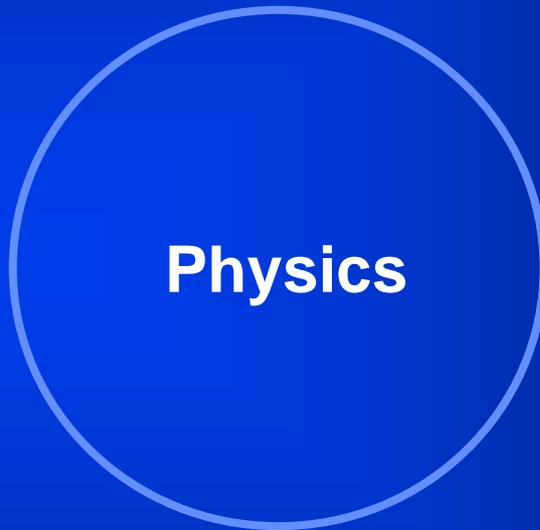
There will be growth in areas of simulation and modeling around the creation of new engineering “structures”. Computer-based design-build engineering ... will become the norm for most product designs, accelerating the creation of complex structures for which multiple subsystems combine to form a final product.

*NAE The Engineer of 2020*

# The Modeling Barrier



*Blockdiagrams ODEs*



*Mass, energy, momentum*

*Block diagrams unsuitable for serious physical modeling*

# Modelica ([www.modelica.org](http://www.modelica.org))

- **Block diagrams and ODEs not suited for physical modeling – the control/physics barrier**
- **Behavior based (declarative) modeling is a good alternative**
- **European activity based on industry/university collaboration**
- **Groups with broad competence and experience**

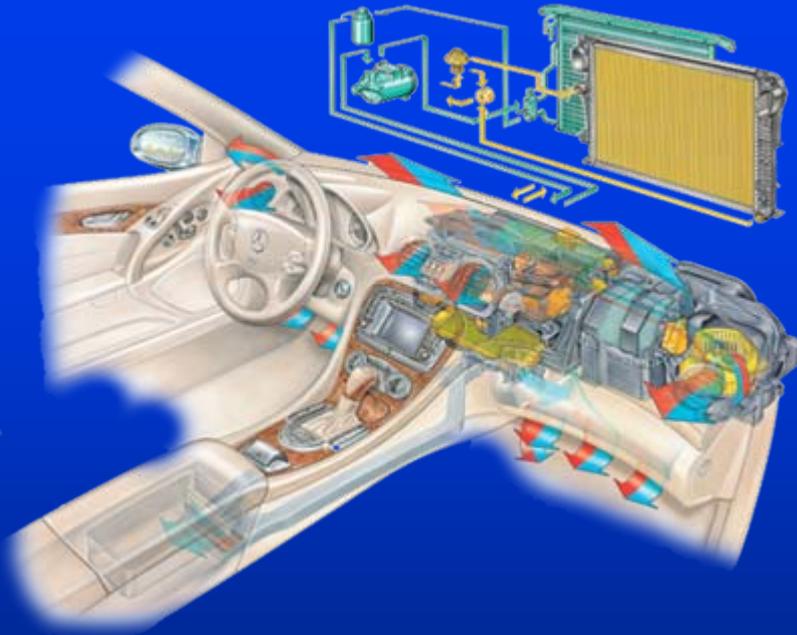


# Modelica ([www.modelica.org](http://www.modelica.org))

- Mimics how an engineer builds a real system
- Object oriented, component-based, multi-domain
- Efficient engineering through reuse
- Model libraries (free and commercial)
- Simulator Dymola (Dynasim)
- Extensive symbolic manipulation, automatic inversion, ...
- Efficient real-time code
- Syntax and semantics formally defined



# Automotive Climate Control



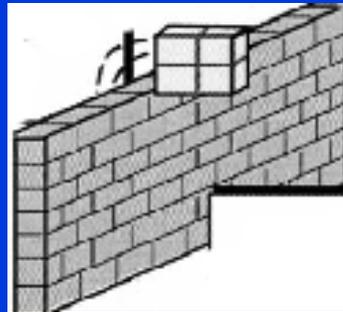
- *Audi, BMW, DaimlerCrysler, Volkswagen and their suppliers have standardized on Modelica*
- *Suppliers provide components and validated Modelica models based on the AirConditioning library from Modelon*
- *Car manufacturers evaluate complete system by simulation*
- *IP protected by extensive encryption*

*Picture courtesy of Behr GmbH & Co.*



# The Implementation Barrier

**Control**



**Computing**

*Feedback, Stability, ODE, PDE*  
*Moderate complexity*  
*Robustness*

*Logic, languages, DES, FSM*  
*High complexity*  
*Abstraction*

*Networked embedded systems*

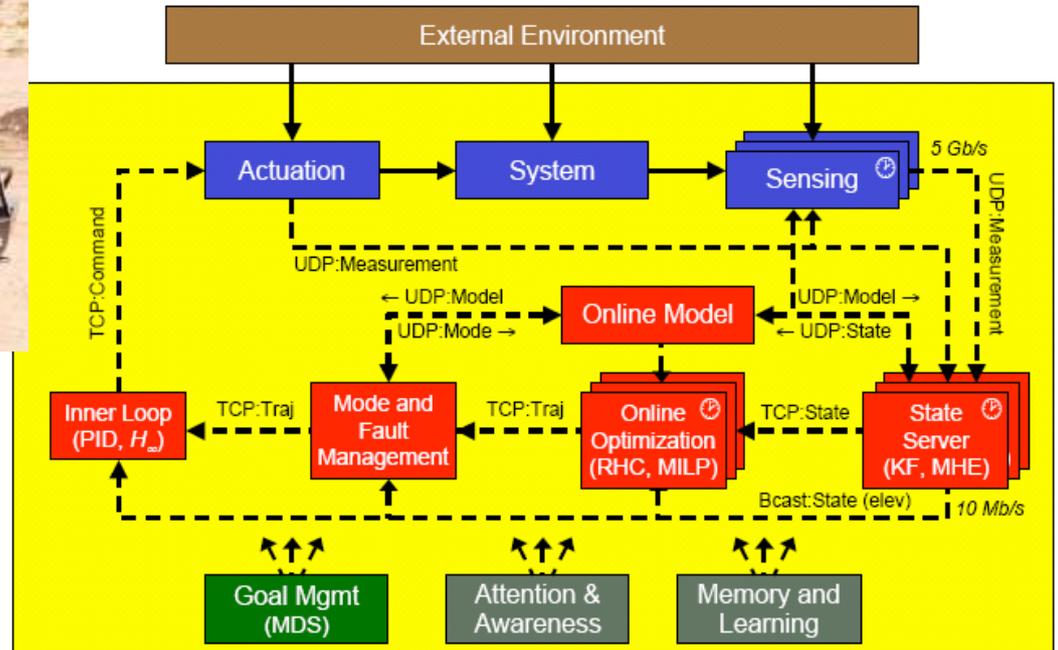
# Safe Design

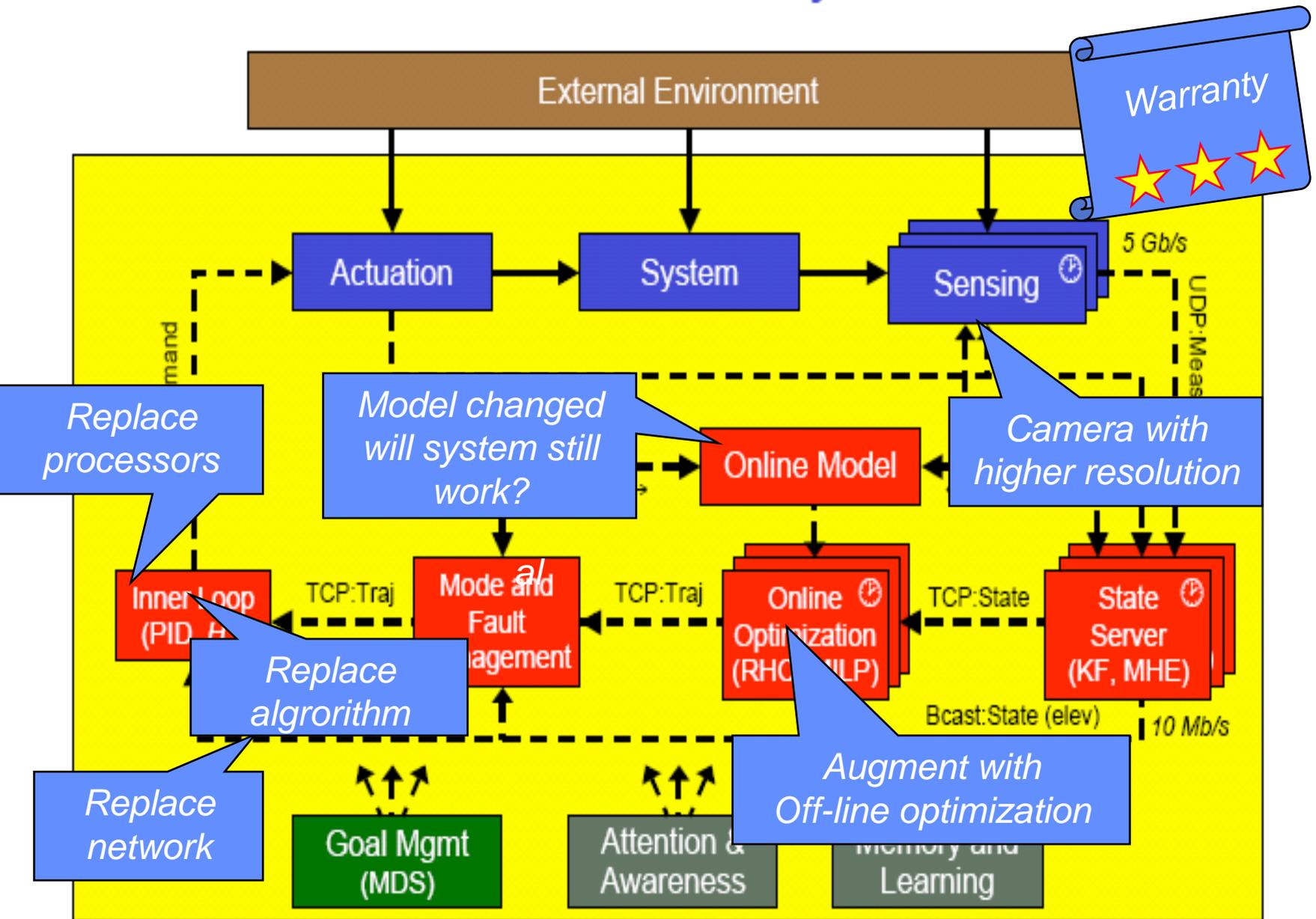
- Much more than automatic code generation
- Formal specification, design, verification and validation
- System architecture
- Integration of subsystems
- Modification, upgrade

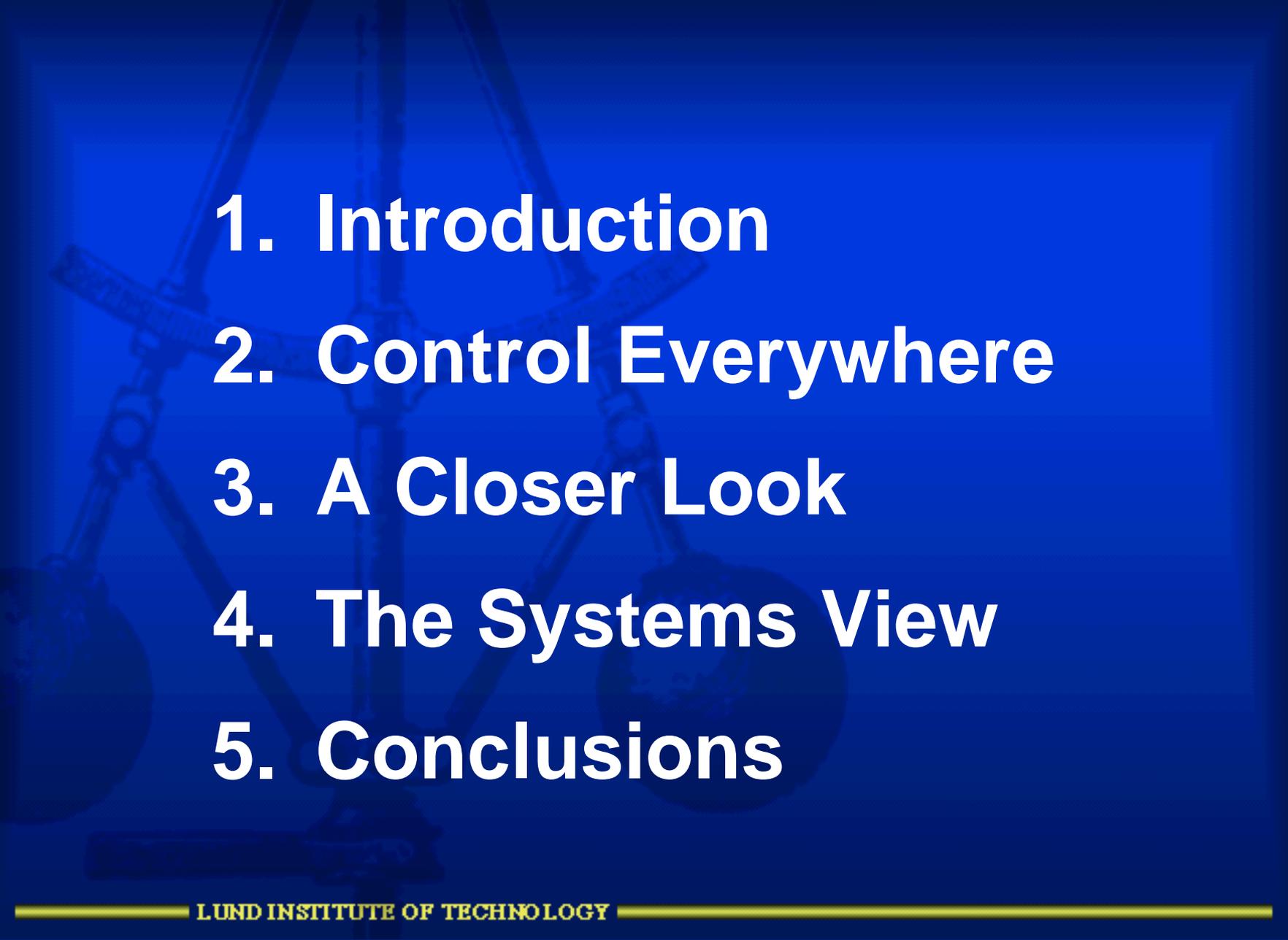
# An Example



*DARPA Grand Challenge  
Caltech Alice*





- 
- 1. Introduction**
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# Conclusions

- Tremendous advances
- Control everywhere
- Massive computations
- The systems challenge
- Like 1956 but at a higher level
- A role for IFAC?

